



Analysis of the Electric Power Monitoring System in Wind Power Plants Based on Arduino Uno

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Abstract - The Wind Power Plant is a renewable energy solution that can reduce dependence on fossil fuels and reduce greenhouse gas emissions. However, to ensure operational efficiency and reliability, an effective monitoring system is needed to monitor and manage the electrical power produced. This research aims to develop and analyze an electrical power monitoring system at PLTB using the Arduino Uno platform. The proposed monitoring system consists of sophisticated sensors integrated with Arduino Uno to collect real-time data regarding wind speed, output voltage, current and turbine operational conditions. The data collected by these sensors is sent to the Arduino Uno, which then processes and stores the data for further analysis. Additionally, this data can be transmitted to other devices for remote monitoring via a wireless communication module. Algorithms were developed to analyze and display critical information about turbine performance, including anomaly detection and failure prediction. System testing was carried out on a small-scale PLTB model, and the results showed that this system was able to monitor changes in electrical power with high accuracy and fast response time. Implementation of this Arduino Uno-based monitoring system also enables early detection of potential problems, so that preventive action can be taken to reduce downtime and increase operational efficiency. The results of this research show that using Arduino Uno as a platform for the electrical power monitoring system at PLTB is not only effective in collecting and analyzing data, but is also economical and easy to implement. This system can be easily adapted and expanded to suit the specific needs of various types of PLTB. In conclusion, the Arduino Uno-based monitoring system offers an innovative and practical solution to improve the performance and reliability of PLTB.

Keywords : Wind Energy, Monitoring, Electric Power, Arduino Uno

1. INTRODUCTION

Electricity sector has an important role in developing countries, not only as an effort to meet needs but also becomes the basis for future technological progress and development. Increasing population and urbanization have an impact on energy demand which also increases, putting great pressure on domestic resources, resulting in independence on electricity [1]. The use of fossil electricity provides a temporary solution to the energy crisis but causes consumer spending additional costs. Developing countries also experience problems due to the inability to meet energy demand and supply, either due to underdeveloped power generation sectors or cessation of transmission capacity which results in electricity shortages. In 2019, around 570 million people in underdeveloped countries did not have access to electricity [2]. Current consumption of fossil fuels will result in the exhaustion of oil, natural gas and coal resources in 50.7, 52.8 and 114 years respectively [3].

Globally, our electricity needs are met by electricity generation, most of which comes from oil, followed by coal, gas, and then hydro electric power plants. The world wide energy mix includes more than 80% of electricity consumption generated from fossil fuels [4]. Fossil fuel sources are responsible for almost ¾ of global greenhouse emissions [4],[5]. The world is currently facing major challenges related to the environment and energy, so switching to renewable and sustainable energy sources is very important. Among the promising options, solar and wind energy are the most prominent, as they have the potential to significantly reduce greenhouse gas emissions and reduce dependence on hydrocarbons [6]. Solar and wind energy are abundant renewable resources available globally, making them important alternatives to conventional fuels due to their sustainability, affordability, and wide accessibility [7]. The application of solar energy and wind turbines has experienced rapid growth in recent years, with many countries setting large targets to increase their dependence on renewable energy [8].

Indonesia is the country with the most islands and has the second longest coastline on the planet (after Canada), with a length of 99,093 km, which has expanded from previously around 91,000 km with wind speeds ranging from 7.2 km/h to 21.6 km/h. The second condition is ideal for using small-scale wind power plants. Wind speed is linear speed that can be obtained by converting the rotation speed obtained by the rotary encoder into linear speed. Wind speed is always changing, so to find out how much energy the wind contains, it is necessary to process wind speed information by utilizing measured information. The heat received by the earth from the sun must pass through the atmosphere first, causing differences in heat in several parts of the atmosphere and the air on earth due to the influence of the gases that make up the layers of air. Wind energy is one of the smartest sources of environmentally friendly energy creation. Wind energy can provide a reasonable answer to the energy emergency and world change [9].

Wind Power Plant (PLTB) is a renewable energy source that is increasingly popular throughout the world as a solution to reduce dependence on fossil fuels and reduce greenhouse gas emissions. Abundant and renewable wind



energy makes PLTB an attractive option to meet increasing global energy needs. However, the operational efficiency and reliability of PLTB is very dependent on a monitoring system that is able to monitor turbine performance in real-time [10].

An effective electrical power monitoring system is needed to ensure that wind turbines operate at optimal conditions and to detect early potential problems that could cause operational losses or damage to the system. The use of Arduino Uno based monitoring technology offers an economical and easy to implement solution for this purpose. Arduino Uno is a flexible and popular microcontroller platform, which can be used to develop various monitoring applications with low cost and minimal complexity [11].

Arduino Uno is equipped with various features that enable the integration of sensors to measure important parameters such as wind speed, voltage, current and frequency of power output from a wind turbine. Data obtained from these sensors can be processed and analyzed to provide accurate and real-time information regarding PLTB operational conditions. In addition, the wireless communication capabilities of the Arduino Uno allow sending data to other devices for remote monitoring, so that operators can take necessary actions quickly and efficiently [12].

Implementation of an Arduino Uno-based monitoring system in PLTB has the potential to increase operational efficiency and reduce maintenance costs by detecting anomalies and predicting failures before they occur. Case studies carried out on various wind turbine models show that the system is capable of providing reliable and consistent performance, and can be adapted to meet the specific needs of various types of geothermal power plants [12].

This research aims to develop and analyze an electrical power monitoring system for a PLTB based on Arduino Uno, with a focus on sensor integration, data collection and processing, and system performance analysis. It is hoped that the results of this research can make a significant contribution to the development of smarter and more efficient monitoring technology for PLTB, as well as support global efforts to increase the use of renewable energy.

2. DEFINITION OF WIND POWER PLAN

2.1 Understanding Wind Energy

Several researchers have conducted research related to wind turbines, including: Bambang Setioko. The increase in fuel prices encourages people to look for new alternatives that are cheap and easy to obtain, so that they can be used for exploration and used as the main driver for electricity generators to supply electricity. Procedures for handling and checking information in the context of assembling wind turbines are made by taking information on the number of fans, spot size, wind speed and number of shocks. Relapse screening is used as a strategy to establish a practical relationship between two factors, especially independent and subordinate factors [13].

For certain wind power and speed, the range, size, height and rotational speed of the rotor can be known. The rotor area is significantly affected by the power coefficient. The design rotor rotational speed can be determined after the rotor width is determined and the tip speed is not completely determined. This study uses a width to average proportion of 0.1:0.8:0.8. The result is a table of force, wind speed, rotor area, density, height and rotational speed which can be used as a basis for planning wind turbines [14].

Wind moving air caused by the rotation of the earth and also due to differences in air pressure. Wind moves from high air pressure to low air pressure. When heated, air expands. Air that has expanded becomes slightly thinner. When this happens, the air pressure drops because there is less air. The cold air around it flows into the low pressure area. The air shrinks and becomes heavier and falls to the ground. Above the ground the air becomes hot again. This flow of rising hot air and falling cold air is due to convection [14].

Wind power refers to the collection of useful energy from the wind. In 2005, the energy capacity of wind power generators was 58,982 MW, resulting in less than 1% of world electricity users. Although still a minor source of electrical energy in most countries, wind power generation more than quadrupled between 1999 and 2005. Most modern wind power is generated in the form of electricity by converting the rotation of turbine blades into electric current using electric generators. In wind mills, wind energy is used to rotate mechanical equipment to perform physical work, such as grinding or pumping water.

2.2 Wind Energy Potential in Indonesia

Based on Government Regulation no. 79 of 2014 concerning National Energy Policy, Indonesia sets a target to achieve a new and renewable energy mix of 23% in 2025 and 31% in 2050. The target capacity for wind power plants (PLT-Wind) in 2025 is 255 MW. However, until 2020, the installed capacity of PLT-Bayu has only reached around 135 MW, with details of 75 MW in Sidrap and 60 MW in Janeponto. This shows that the development of wind energy in Indonesia still faces big challenges to achieve this national target [15], [4].

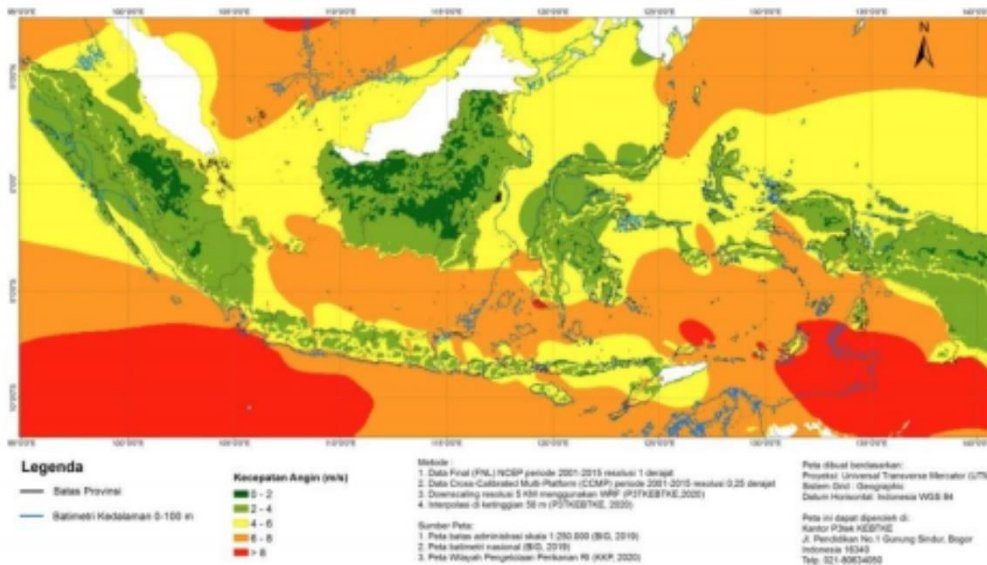


Figure 1: Map of Wind Distribution in Indonesia

The availability of accurate wind energy potential maps throughout Indonesia is very necessary as a first step in identifying and selecting locations for wind energy projects. This map provides important information regarding wind characteristics in various regions, such as average wind speed, as well as maximum and minimum speeds which can be converted into power density maps and annual energy maps (in kWh or W/m²). This information is very useful as a basis for determining project locations and selecting appropriate turbine technology [16], [17].

Based on the results of wind speed distribution mapping, it was found that high wind speeds (6-8 m/s) in the onshore area occurred on the southern coast of Java, South Sulawesi, Maluku and East Nusa Tenggara (NTT). Meanwhile, in the offshore area, wind speeds of more than 8 m/s were detected at Offshore Banten, Offshore Sukabumi, Offshore Kupang, Offshore Pulau Wetar, Offshore Jeneponto Regency, and Offshore Tanimbar Islands Regency. Maximum wind speeds occur in June, July and August (JJA) during the Australian monsoon season, while minimum speeds occur in March, April and May (MAM) during the transition from the Asian monsoon to the Australian monsoon [16].

2.3 Types of Wind Turbines

A wind turbine is a windmill used to generate power. This wind turbine was originally created to meet the needs of farmers in processing rice, water management needs, and so on. Many wind turbines of the past were developed in Denmark, the Netherlands and other European countries and were also called Windmills, including the Horizontal Axis wind turbine (HAWT) having a primary rotor shaft and an electric generator at the highest point of the peak. Small turbines are coordinated by direct wind vanes (climate vanes), while large turbines generally use wind sensors combined with servo machines. Most of them have a box. Wind turbines have several types including: gears that change the slow wheel shaft to a faster one [18].

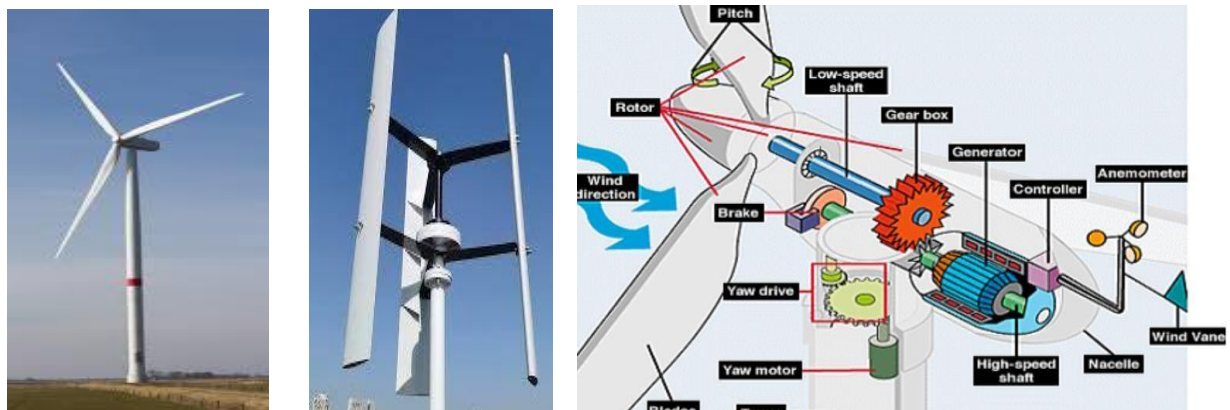


Figure 2. Wind Turbine and Wind Turbine Components



2.4 Arduino Uno

Arduino Uno is a board that uses the ATmega328 microcontroller. The Arduino Uno has 14 digital pins (6 pins can be used as PWM outputs), 6 analog inputs, a 16 MHz crystal oscillator, a USB connection, a voltage source connector, an ICSP header, and a reset button. Arduino Uno contains everything needed to support a microcontroller. Just by connecting it to a computer via USB or providing DC voltage from a battery or AC to DC adapter can make it work. Arduino Uno uses an ATmega16U2 which is programmed as a USB to serial converter for serial communication to a computer via a USB port [12].

Arduino Uno is a very popular microcontroller and is often used in electronic projects and embedded systems. The working principle of the Arduino Uno involves processing digital and analog signals to control various hardware devices through programming written in the Arduino Integrated Development Environment (IDE). The following is an explanation of the working principle of Arduino Uno [12].

Basic Structure Arduino Uno consists of several main components:

- **ATmega328P Microcontroller:** This is the core of the Arduino Uno which is responsible for running the uploaded programs.
- **Digital and Analog Pins:** Arduino Uno has 14 digital I/O pins and 6 analog input pins which are used to read signals from sensors or control actuators.
- **Voltage Regulator:** Ensures that the microcontroller and other components get a stable voltage.
- **USB Connection:** Used to upload programs from the computer to the microcontroller and can also be used to provide power to the board.
- **Memory:** The ATmega328P has flash memory for storing programs, SRAM for temporary data, and EEPROM for long-term data storage.

Working Principle Steps

- **Program Writing:** Programs are written in the Arduino programming language which is similar to C/C++ in the Arduino IDE.
- **Program Compilation:** The written program is compiled in the Arduino IDE into binary code that can be understood by the ATmega328P microcontroller.
- **Program Upload:** The binary code is uploaded to the microcontroller's flash memory via a USB connection using the integrated bootloader protocol.
- **Program Execution:** Once uploaded, the microcontroller immediately executes the program that has been uploaded. This program can be a loop that continues to run as long as the Arduino is powered.
- **Input and Output Processing:** The microcontroller reads input from digital and analog pins, processes the data according to program logic, and produces appropriate output via digital or PWM (Pulse Width Modulation) pins.
- **Interaction with Hardware:** Arduino Uno can interact with various hardware such as sensors, motors, LEDs, and communication modules. For example, a temperature sensor can provide analog input to a microcontroller, which is then processed to control fan speed via a PWM output.

Arduino Uno works by reading input from sensors and other devices, processing the input according to the uploaded program, and producing output that controls other devices. With its simple structure and flexible programming capabilities, the Arduino Uno is a very useful tool in the development of electronic and automation systems.



Figure 3. Arduino Uno, Current Sensor and Voltage Sensor

2.5 Current Sensor

A current sensor is a device used to measure the flow of electric current in a circuit. Current measurement is important for a variety of applications, including power monitoring, electrical system protection, and measuring the efficiency of electronic devices. Current sensors work by converting the electric current passing through them into a voltage or digital signal that can be measured and analyzed. Current sensors play an important role in a variety of electronic and electrical applications by providing an accurate and reliable way to measure current. Understanding the



working principles and types of current sensors available helps in selecting the right sensor for a particular application, ensuring accurate measurements and optimal system protection [19] [20] .

2.6 Sensor PZEM-0042.7

PZEM-004T is a sensor that can be used to measure rms voltage, rms current and active power which can be connected via Arduino or other open source platform forms. The physical dimension of the PZEM-004T board are 3.1 × 7.4 cm. The PZEM-004T

Module is bundled with a 3 mm diameter current transformer coil which can be used to measure a maximum current of 100A .

3. RESEARCH METHODOLOGY

A system flowchart is a diagram that explains program flow starting from start to finish in one processor or one work cycle. In this case, System Flowchart work begins with initialization and initial values. After that the system will start to arrange connection WiFi, Arrange connection WiFi will start with connect module ESP-01 to SSID which has registered. If ESP 8266 does not find or connect to the SSID, then the system will keep trying to connect the system by SSID until it connects. After connected, then the system will start reading the voltage and current sensors and processing their data from sensors become marks which can be understood by users. The marks will be displayed on the LCD and sent to the Thingspeak server via an network connection WiFi which has connected.

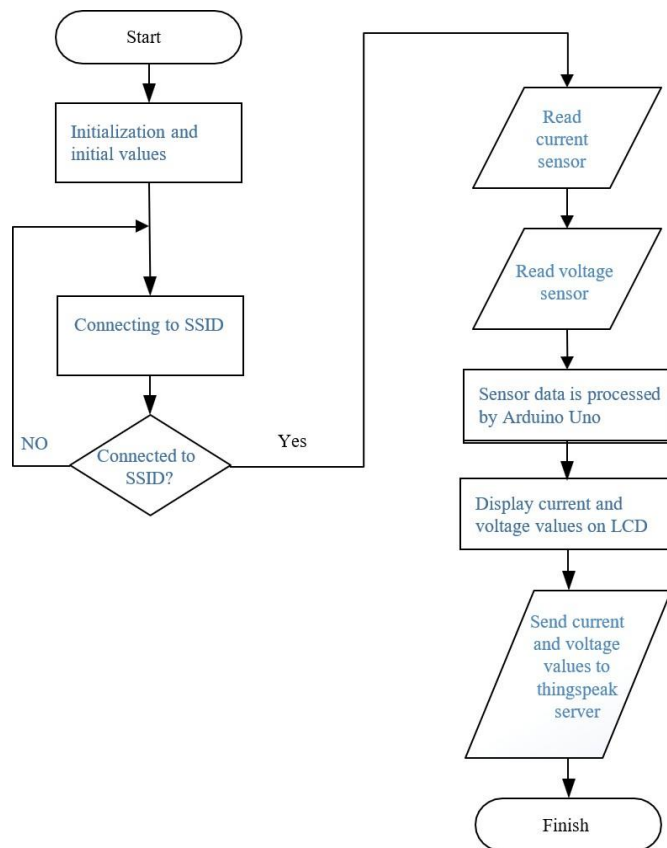


Figure 4. Research Flow Diagram

The equation used in this research is:

$$V_{out} = V_{in} \times \left(\frac{R_1}{R_1 + R_2} \right) \quad (1)$$

$$I = V/R \quad (2)$$



4. RESULTS

Results Study is an analysis from implementation study which has been carried out, there are search results in the form of a prototype model of the turbine monitoring system which consists of a blade wind turbine, charge controller, battery and monitoring system. The wind turbine blades will rotate if something blows towards them. Wind turbine blades will rotate the generator contained in the wind turbine will produce an electric voltage which is then output from that voltage will be connected to the charge controller using a cable. Charge controller will control the electrical power from the wind turbine to keep it stable to recharge the battery even though the electrical power produced by the wind turbine is not stable and functionally as a safety so that voltage battery does not flow to generator turbine wind when the wind turbine does not produce any electrical power at all.

Monitoring system consists of analog and digital electronic circuits. The system consists of a power supply, current sensor, voltage sensor, Arduino microcontroller, ESP-01 chip, LCD. The system consists of 2AC712 current sensors, each measuring current. The charge controller actively recharges the battery and measures the output current battery when also disconnected. To measure battery voltage, a circuit is used to divide voltage. Arduino also controls delivery data to LCD for display of current and voltage sensor readings. The ESP-01 chip works in a region which relates with delivery data via WiFi, data results measurement.

4.1 Current Sensor Test Results

Current sensor ACS712 works based on technology Hall effect. This sensor is a low-offset linear Hall with one trajectory which is made of copper. The way this sensor works is that the current flows through the copper track contained inside which produces a field magnet which is caught by the integrated Hall I.C. Generate current electricity which results in a magnet which induces part *dynamic offset cancellation* from ACS712, part of this will be strengthened by *amplifiers* and through *filters* which convert it into a proportional voltage. For measurement which passes sensors, this used formula voltage at pin $Out = 2.5 \pm (0.185 \times I)$ Volts, where I = current detected in Ampere units. Testing to find out what the sensor is working and functioning properly can be done by providing a power supply on sensors. Then sensors given variation burden resistor

Table 1: Current Sensor Test Results

No	Mark resistor (ohms)	Voltage source (volt)	Current calculation (amperes)	Mark reading sensor (amperage)	% error
1	3	12.83	4.28	4.50	1.74
2	5	12.74	2.55	2.80	1.98
3	7	12.80	1.83	2.03	1.57
4	10	12.76	1.28	1.54	2.07
5	13	12.81	0.99	1.15	1.29
6	16	12.85	0.80	0.92	0.91
7	20	12.77	0.64	0.75	0.87
8	25	12.78	0.51	0.66	1.16
9	30	12.80	0.43	0.54	0.89
10	35	12.80	0.37	0.45	0.66
Average					1.31

4.2 Testing Suite Divider Voltage

Voltage Dividers or Divider Voltage is something simple method that converts a large voltage into a smaller voltage. The Voltage Divider Rule is that the input voltage is divided proportionally according to the resistance value of two resistors connected in series. Testing Suite divider voltage with give supply Power on Suite divider voltage. Mark voltage on output output connected to the positive probe of the multimeter and the negative probe of the multimeter connected to power supply ground or ground and divider circuit ground voltage. The voltage value at the output of the voltage divider circuit also read by Arduino and displayed on the serial monitor. Here are the results testing voltage divider circuit.

Table 2: Voltage Divider Circuit Test Results

No	Reading Multimeter (volts)	Outputs Arduino (volts)	% Error
1	0.00	0.00	0.00
2	1.11	1.18	3.50
3	2.14	2.10	1.33
4	3.10	3.18	2.00
5	4.15	4.05	2.00
6	5.14	5.28	2.33



4.3 Testing Cat Power or Regulators

The power supply used is a 12 VDC VRLA battery. Regulators LM2596 regulator is used to provide constant voltage supply 5 volt on series system And sensors. Testing done with give supply input And use multimeter For measure input voltage and output voltage in both circuits. Supply voltage input comes from a 12 volt DC battery

Table 3: Power Supply and Regulator Test Results

Condition	Inputs VCC (volt)	LM 2596 outputs (5 volt)
Without Burden	12,10	5.00
With Burden	11.80	4.99

4.4 Conclusion

This research has provided in-depth insight into the theory and working principles of various types of current sensors, including shunt resistors, Hall effect sensors, current transformers (CT), and optical current sensors. Each type of sensor has a unique working principle and different advantages and disadvantages, which affect their application in various situations. This research focus is that selecting the right type of current sensor is very important and must be based on the specific needs of the application. Current sensors have an important role in power monitoring, electrical system protection, efficiency measurement, and battery charging. By understanding the working principles of each sensor, we can optimize their use for various electronic and electrical applications. Proper implementation of current sensors not only improves measurement accuracy, but also improves overall system reliability and efficiency. This research also shows the importance of sensor calibration and maintenance to ensure optimal performance. As a crucial tool in various industries, effective and reliable current sensors can help in developing smarter and more sustainable energy solutions.

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We hope that the results of this research can make a significant contribution to the field of flow monitoring system development and can become a basis for further research.

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